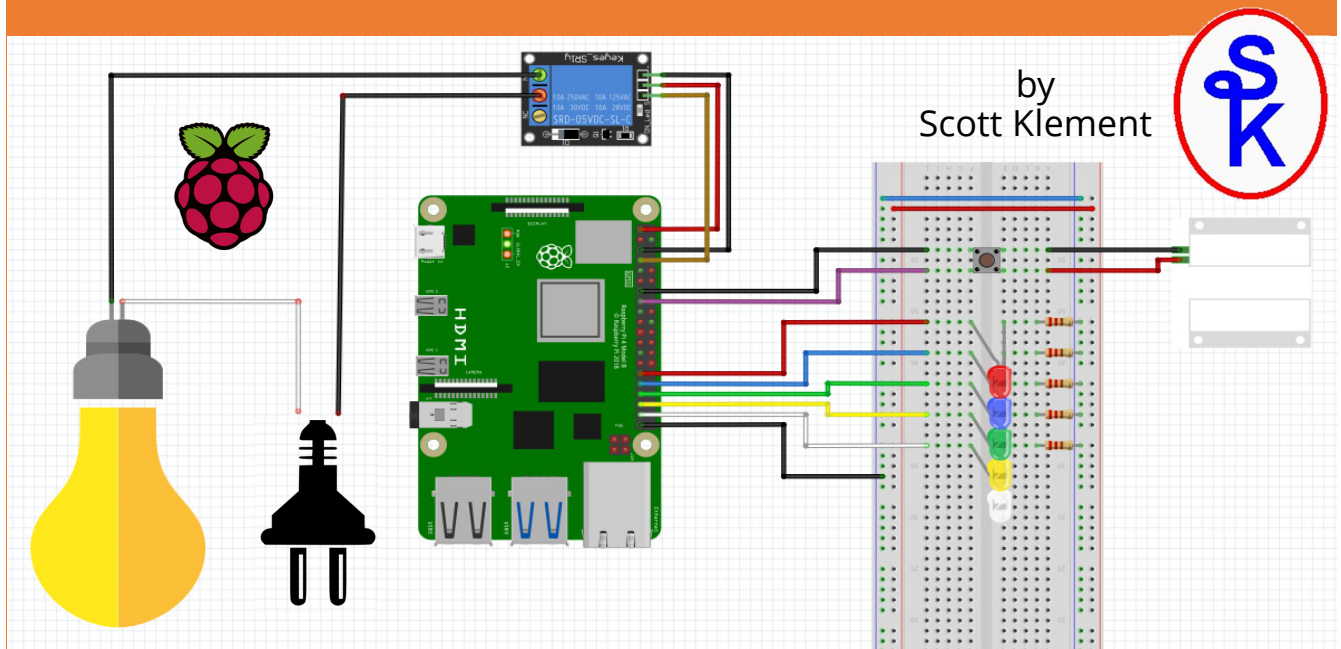


# A First Look at Physical Computing With Raspberry Pi



Two Raspberry Pi computers (with my hand for comparison)

- Zero-W (approx. \$10)
- 4B 4GB (approx. \$60)



## What?

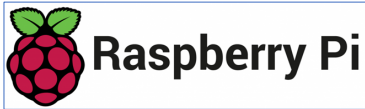
The Raspberry Pi is a small, inexpensive, energy efficient computer.

- Storage on microSD cards
- HDMI video/audio
- USB ports for keyboard/mouse
- Wired & Wifi Networking
- ARM-based CPU
- GPIO pins

# Why?

Small, efficient, and inexpensive.

- Stick it under a table
- Back of a monitor
- Inside/above/under a cabinet
- Inside a vehicle
- ...really, anywhere...



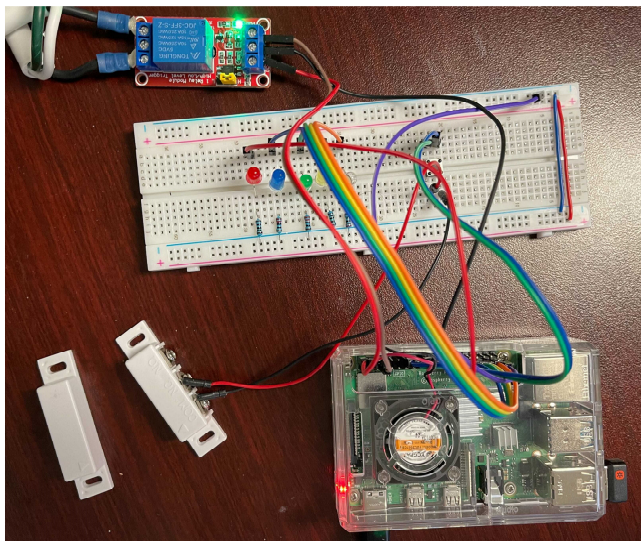
Use it to control electronics, and interface with a bigger computer.

- Such as your PC
- Power Systems running IBM i

Write your own custom application that controls the GPIO pins, and make it do whatever you want.

- Turn stuff on or off.
- Read sensors (temperature, pressure, "eyes"/infrared, cameras)
- Make conveyors move.
- Interface printers, scanners, scales, industrial terminals...
- The possibilities are endless!
- Motors/Servos
- Ultrasonic sensors
- Solenoid valves

# Show Me!



Simple demonstration of

- Turn LEDs on/off.
- Turn Power (Lamp) on/off.
- Read a door sensor.

# Imagine...

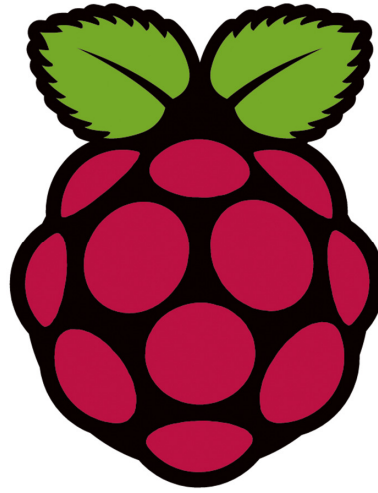
I demonstrated turning LEDs and a light on/off.

Think of all of the other things you could turn off!

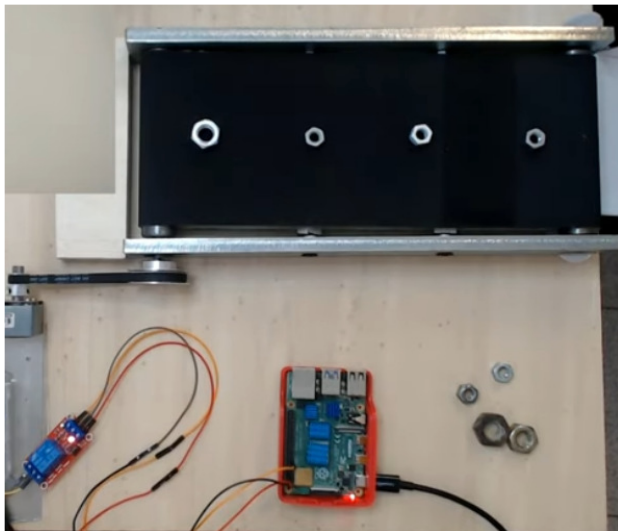
And it's done by program logic, so could be done under any logic you can imagine.

Likewise, I demonstrated reading from a switch.

Think of all of the other sensors and devices you can read from.



# Conveyor

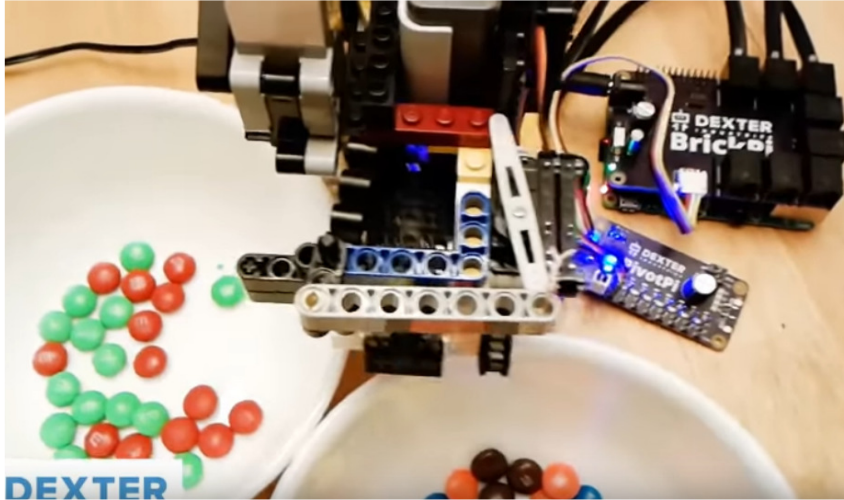


There are cameras available that work well with image detection software (such as OpenCV)

This project stops the conveyor belt when a nut over a given size is detected at the end of the conveyor. The worker could then remove the one that's too large.

With servos you could build a robotic arm (or buy a prebuilt one) that removes the nut. (Or any other type of item.) -- not shown.

# Sorting M&Ms



Sorts M&Ms by color. Pretty cool, to play with -- but there are also industrial uses for it.

In Node.js, I use the open source onoff module to interact with the gpio pins.

To turn one on, you simply write 1 to it. To turn it off, write 0.

```
var Gpio = require("onoff").Gpio;

var led = new Gpio(5, 'out');

// Turn on
led.writeSync(1);

// Turn off after 5 seconds
setTimeout(() => led.writeSync(0), 3000);
```

## Programming GPIO

3v3 Power	1	•	•	2	5v Power
GPIO 2 (I2C1 SDA)	3	•	•	4	5v Power
GPIO 3 (I2C1 SCL)	5	•	•	6	Ground
GPIO 4 (GPCLK0)	7	•	•	8	GPIO 14 (UART TX)
Ground	9	•	•	10	GPIO 15 (UART RX)
GPIO 17	11	•	•	12	GPIO 18 (PCM CLK)
GPIO 27	13	•	•	14	Ground
GPIO 22	15	•	•	16	GPIO 23
3v3 Power	17	•	•	18	GPIO 24
GPIO 10 (SPI0 MOSI)	19	•	•	20	Ground
GPIO 9 (SPI0 MISO)	21	•	•	22	GPIO 25
GPIO 11 (SPI0 SCLK)	23	•	•	24	GPIO 8 (SPI0 CE0)
Ground	25	•	•	26	GPIO 7 (SPI0 CE1)
GPIO 0 (EEPROM SDA)	27	•	•	28	GPIO 1 (EEPROM SCL)
GPIO 5	29	•	•	30	Ground
GPIO 6	31	•	•	32	GPIO 12 (PWM0)
GPIO 13 (PWM1)	33	•	•	34	Ground
GPIO 19 (PCM FS)	35	•	•	36	GPIO 16
GPIO 26	37	•	•	38	GPIO 20 (PCM DIN)
Ground	39	•	•	40	GPIO 21 (PCM DOUT)

In Raspberry Pi, you can read from pin (even if in 'out' mode)

This makes it easy to toggle.

```
var Gpio = require("onoff").Gpio;

var relay = new Gpio(4, 'out');

function toggle() {
  var currentValue = relay.readSync();
  relay.writeSync(currentValue ^ 1);
}

toggle();
setTimeout(toggle, 3000);
```

# GPIO Toggle

3v3 Power	1	2	5v Power
GPIO 2 (I2C1 SDA)	3	4	5v Power
GPIO 3 (I2C1 SCL)	5	6	Ground
GPIO 4 (GPCLK0)	7	8	GPIO 14 (UART TX)
Ground	9	10	GPIO 15 (UART RX)
GPIO 17	11	12	GPIO 18 (PCM CLK)
GPIO 27	13	14	Ground
GPIO 22	15	16	GPIO 23
3v3 Power	17	18	GPIO 24
GPIO 10 (SPI0 MOSI)	19	20	Ground
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GPIO 0 (EEPROM SDA)	27	28	GPIO 1 (EEPROM SCL)
GPIO 5	29	30	Ground
GPIO 6	31	32	GPIO 12 (PWM0)
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GPIO 19 (PCM FS)	35	36	GPIO 16
GPIO 26	37	38	GPIO 20 (PCM DIN)
Ground	39	40	GPIO 21 (PCM DOUT)

Naturally, you can read the same way you do a write. But, how do you know when to read?

onoff provides a watch event that can fire a function when the state of a button changes. It can be 'falling' (switch closing), 'rising' (switch opening) or 'both'.

There's also a debounceTimeout to avoid the situation where a button might open/close more than once rapidly.

```
var Gpio = require("onoff").Gpio;

var button = new Gpio(23, 'in', 'both',
  {debounceTimeout: 10});

button.watch((err, value) => {
  console.log((value===1) ? 'up': 'down');
});
```

# Async Button

3v3 Power	1	2	5v Power
GPIO 2 (I2C1 SDA)	3	4	5v Power
GPIO 3 (I2C1 SCL)	5	6	Ground
GPIO 4 (GPCLK0)	7	8	GPIO 14 (UART TX)
Ground	9	10	GPIO 15 (UART RX)
GPIO 17	11	12	GPIO 18 (PCM CLK)
GPIO 27	13	14	Ground
GPIO 22	15	16	GPIO 23
3v3 Power	17	18	GPIO 24
GPIO 10 (SPI0 MOSI)	19	20	Ground
GPIO 9 (SPI0 MISO)	21	22	GPIO 25
GPIO 11 (SPI0 SCLK)	23	24	GPIO 8 (SPI0 CE0)
Ground	25	26	GPIO 7 (SPI0 CE1)
GPIO 0 (EEPROM SDA)	27	28	GPIO 1 (EEPROM SCL)
GPIO 5	29	30	Ground
GPIO 6	31	32	GPIO 12 (PWM0)
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GPIO 19 (PCM FS)	35	36	GPIO 16
GPIO 26	37	38	GPIO 20 (PCM DIN)
Ground	39	40	GPIO 21 (PCM DOUT)

# The End.



The code to write the REST API and communicate with RPG is too much to show you here.

But it is similar to any other REST API you might code.

The entire code is on GitHub, if you want to see it.

<https://github.com/ScottKlement/rpg-raspi-demo>

Likewise, working with cameras, servos, ultrasonics, and more is possible, but too much for a 20 minute session. There's tons of examples and sample projects online, though -- just google it!

Before you know it, you'll be interacting with the physical world, doing physical computing.